

VI Approximation and Stability

A. Approximation of continuous functions

differential topology is about smooth functions but many times we only have continuous information so we begin with

Th^m 1:

Suppose M is a smooth manifold and

$f: M \rightarrow \mathbb{R}^k$ is a continuous function

given any continuous positive function

$$\delta: M \rightarrow \mathbb{R}$$

there is a smooth function $\hat{f}: M \rightarrow \mathbb{R}^k$

such that

$$\|f(x) - \hat{f}(x)\| < \delta(x) \quad \forall x \in M$$

if f is already smooth on a closed subset $A \subset M$

then we can take $\hat{f} = f$ on A

"can jiggle a continuous function to make it smooth"

"smooth functions are dense in continuous functions"

for the proof we need the following

given an open cover $\{U_\alpha\}_{\alpha \in A}$ of a manifold M , then

a partition of unity subordinate to $\{U_\alpha\}$ is

a family of functions $\{\psi_\alpha: M \rightarrow \mathbb{R}\}_{\alpha \in A}$ such that

- ① $0 \leq \psi_\alpha(x) \leq 1 \quad \forall \alpha \in A \text{ and } x \in M$
- ② support of $\psi_\alpha \subset U_\alpha \quad \forall \alpha \in A$
- ③ $\forall x, \exists$ a nbhd V_x s.t. $\psi_\alpha|_{V_x} \equiv 0$ for all but finitely many α
- ④ $\sum_{\alpha \in A} \psi_\alpha(x) = 1 \quad \forall x \in M$

lemma 2:

any open cover of a smooth manifold admits a partition of unity subordinate to it

Proof: "Manifolds are paracompact"

need Hausdorff and second countable for this see text book

i.e. given $\{U_\alpha\}_{\alpha \in A}$ an open

cover, can find an open cover $\{V_\beta\}_{\beta \in B}$

by sets homeomorphic to open balls in coordinate charts s.t. $\forall \beta \in B, \exists \alpha \in A$

s.t. $V_\beta \subset U_\alpha$ and $\{V_\beta\}$ are "locally finite"

(that is satisfy ③ above)

now for each $\beta \in B$ take a bump function

$$f_\beta: M \rightarrow \mathbb{R}$$

s.t. $f_\beta > 0$ on V_β and $= 0$ on $M - V_\beta$

choose a function $i: B \rightarrow A$ s.t. $V_\beta \subset U_{i(\beta)}$

and set

$$\tilde{\Psi}_\alpha(x) = \sum_{\substack{\beta \in B \\ i(\beta) = \alpha}} f_\beta(x)$$

$$\Psi(x) = \sum_{\alpha \in A} \tilde{\Psi}_\alpha(x)$$

and

$$\Psi_\alpha(x) = \tilde{\Psi}_\alpha(x) / \Psi(x)$$



Cor 3:

Suppose M a smooth manifold

A a closed subset and

$f: A \rightarrow \mathbb{R}^k$ a smooth function

for any open set U containing A , \exists a smooth

function $\tilde{f}: M \rightarrow \mathbb{R}^k$

such that $\tilde{f} = f$ on A and $\text{support } \tilde{f} \subset U$

Proof: by defⁿ of "smooth on A " we know

for each $a \in A$, \exists an open set W_a and a

smooth function $f_a: W_a \rightarrow \mathbb{R}^k$ s.t. $f_a = f$ on $W_a \cap A$

and we can assume $W_a \subset U$ (by intersection)

$\{W_a\}_{a \in A} \cup \{M \setminus A\}$ is an open cover of M

so there is a partition of unity $\{\psi_a\}_{a \in A} \cup \{\psi_0\}$

subordinate to it

$$\text{set } \tilde{f}_a : M \rightarrow \mathbb{R}^k : x \mapsto \begin{cases} \psi_a(x) f_a(x) & x \in W_a \\ 0 & x \notin W_a \end{cases}$$

these are smooth on all of M

and since $W_a \subset U$, the functions are 0 outside U

$$\text{set } \tilde{f}(x) = \sum_{a \in A} \tilde{f}_a(x)$$

↖ note: finite sum since ψ_a are locally finite

clearly $\text{support } \tilde{f} \subset U$

and

$$\begin{aligned} x \in A, \quad \tilde{f}(x) &= \sum \psi_a(x) f_a(x) \\ &= f_a(x) \sum \psi_a(x) = f_a(x) \end{aligned}$$



Proof of Th^m 1:

by Cor 3 \exists a smooth function $\tilde{f} : M \rightarrow \mathbb{R}^k$

that agrees with f on A

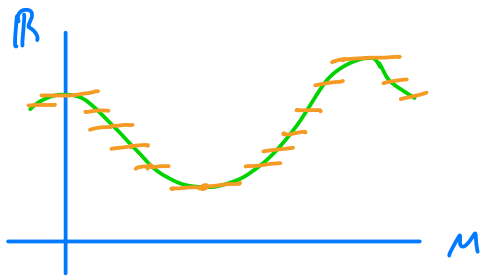
$$\text{let } U_0 = \{x \in M : \|f(x) - \tilde{f}(x)\| < \delta(x)\}$$

this is an open set (check this!) containing A

we now use the continuity of f to construct a "nice cover" of M

for each $x \in M - A$, \exists a nbhd U_x of x in $M - A$ st

$$\left. \begin{aligned} \delta(y) &> \frac{1}{2} \delta(x) \text{ and} \\ \|f(y) - f(x)\| &< \frac{1}{2} \delta(x) \quad \forall y \in U_x \end{aligned} \right\} \text{continuity!}$$



$\{U_x\}$ is a cover of $M - A$

since M is second countable \exists a countable subcover $\{U_{x_i}\}_{i=1}^{\infty}$
 let $\{\psi_0, \psi_i\}$ be a partition of unity subord. to $\{U_0, U_{x_i}\}_{i=1}^{\infty}$

set

$$\hat{f}(y) = \psi_0(y) \tilde{f}(y) + \sum_{i=1}^{\infty} \psi_i(y) f(x_i)$$

\hat{f} is smooth and equal to f on A

now $\|\hat{f}(y) - f(y)\| = \|\psi_0(y) \tilde{f}(y) + \sum_{i=1}^{\infty} \psi_i(y) f(x_i) - (\psi_0(y) + \sum_{i=1}^{\infty} \psi_i(y)) f(y)\|$

$$\leq \psi_0(y) \|\tilde{f}(y) - f(y)\| + \sum_{i=1}^{\infty} \psi_i(y) \|f(x_i) - f(y)\|$$

$$< \psi_0(y) \delta(y) + \sum_{i=1}^{\infty} \psi_i(y) \frac{1}{2} \delta(x_i)$$

$$< (\psi_0(y) + \sum_{i=1}^{\infty} \psi_i(y)) \delta(y) = \delta(y)$$

We would like a similar theorem for $f: M \rightarrow N$ but no notion of distance in N so need something new!

B. Normal bundles and tubular neighborhoods

to continue our discussion of approximations we need normal bundles

given a vector bundle $\begin{array}{c} E \\ \downarrow p \\ M \end{array}$ and a subbundle $\begin{array}{c} G \subset E \\ \downarrow p \downarrow \\ M \end{array}$

with fiber dimension of E equal to n and

of G equal to k

$$\text{then set } E/G = \bigcup_{x \in M} E_x/G_x$$

here E_x is the fiber of E above x
and similarly for G_x

let $q: E/G \rightarrow M$ be the obvious projection
to see E/G is a vector bundle we need local
trivializations

$$\begin{array}{ccc} U \times \mathbb{R}^n & \xrightarrow{\phi} & p^{-1}(U) \\ p_1 \searrow & & \swarrow p \\ & U & \end{array} \quad \begin{array}{l} \text{be a local} \\ \text{trivialization of } E \end{array}$$

note for each $x \in U$, $\phi^{-1}(G_x)$ is a k -dimensional
subspace of \mathbb{R}^n and there is a matrix A_x
such that $A_x(\mathbb{R}^k \times \{0\}) = \phi^{-1}(G_x)$

exercise: $A: U \rightarrow GL(n, \mathbb{R}): x \mapsto A_x$ is smooth

$$\begin{array}{ccc} U \times \mathbb{R}^k & \longrightarrow & (p|_G)^{-1}(U) \\ \uparrow & & \uparrow \\ U \times \mathbb{R}^n & \xrightarrow{\tilde{\phi}} & p^{-1}(U) \\ p_1 \searrow & & \swarrow p \\ & U & \end{array} \quad \tilde{\phi}(x, v) = \phi(x, A_x(v))$$

and $\tilde{\phi}$ thus induces a map

$$\begin{array}{ccc}
 U \times \mathbb{R}^{n-k} & & \\
 \parallel & & \\
 U \times \mathbb{R}^n / \mathbb{R}^k & \xrightarrow{\hat{\phi}} & q^{-1}(U) \\
 p_1 \downarrow & & \swarrow q \\
 & & U
 \end{array}$$

so E/G is an $(n-k)$ -vector bundle

exercise: if G' is a subbundle of E st. $G_x \oplus G'_x = E_x$
 $\forall x \in M$
 then \exists an isomorphism

$$\begin{array}{ccc}
 \psi: G' & \rightarrow & E/G \\
 \downarrow \circ \downarrow & & \swarrow \\
 & & M
 \end{array}$$

now if S is a submanifold of M then TS is a subbundle of $TM|_S$

we define the normal bundle of S in M to be

$$\nu_M(S) = TM|_S / TS$$

note: if M is a submanifold of \mathbb{R}^n then set

$$TM^\perp = \{v \in T_x \mathbb{R}^n \mid x \in M \text{ and } v \perp T_x M\}$$

clearly at each point $x \in M$

Euclidean inner product on \mathbb{R}^k

$$T_x \mathbb{R}^n = T_x M \oplus (TM^\perp)_x$$

so by the above $\nu_{\mathbb{R}^k}(M) \cong TM^\perp$

this is why we call it the normal bundle
(you can do this for any S in M but need M
to have an inner product on each $T_x M$
i.e. a Riemannian metric)

Thm 4:

if M^m is a compact submanifold of \mathbb{R}^n then
in any open neighborhood V of M , \exists an open
set $N(M)$ containing M s.t. $N(M)$ is an open disk
bundle over M : $B^{n-m} \rightarrow N(M)$

$\downarrow q$
 M

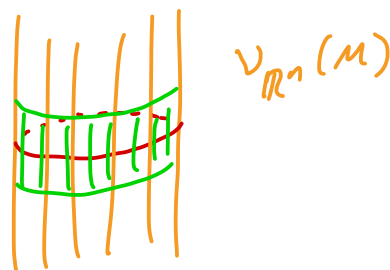
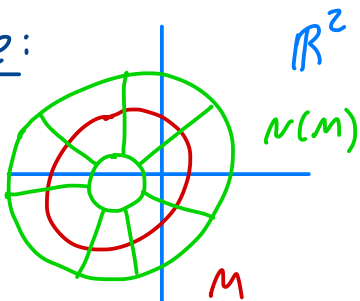
and \exists a subdisk bundle $N' \subset \nu_{\mathbb{R}^n}(M)$ s.t.

$$N' \cong N(M)$$

In particular, $q: N(M) \rightarrow M$ is the identity
on M and q is a submersion

Remarks: 1) true if M is non-compact too
2) true for any submanifold S of M

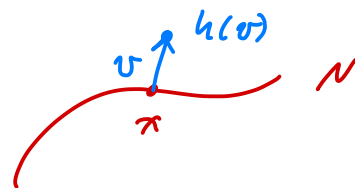
example:



Proof: recall $\nu(M) \cong TM^\perp$

let $h: TM^\perp \rightarrow \mathbb{R}^n$

$$v \in (T_x M)^\perp \mapsto \underset{x}{p(v)} + v$$



recall $p(x) \in M \subset \mathbb{R}^n$
 $v \in T_x \mathbb{R}^n = \mathbb{R}^n$

let $Z = \{\text{zero vectors in } TM^\perp\}$

note: any $v \in Z$ is a regular point of h

indeed: $T_{p(v)} \mathbb{R}^n = \mathbb{R}^n = T_{p(v)} M \oplus (TM)_{p(v)}^\perp$

and $\begin{array}{c} TM^\perp \\ p \downarrow \uparrow \sigma \\ M \end{array}$ where $\sigma(x) = 0 \in (TM)_x^\perp$
and $p \circ \sigma = \text{id}_M$

so $p|_Z$ and σ are inverses of each other

so $p|_Z$ is a diffeomorphism $Z \rightarrow M$

\therefore along Z dp_v maps onto $T_{p(v)} M$

now $dh|_{TM^\perp_{p(v)}}$ maps onto the linear space

$$TM^\perp_{p(v)} \subset T_{p(v)} \mathbb{R}^n$$

so image $dh_{p(v)} = T_{p(v)} \mathbb{R}^n$

thus since $\dim TM^\perp$ and \mathbb{R}^n are same h is a local diffeomorphism along Z and \therefore in a neighborhood of Z

(any nbhd of Z contains a subdisk bundle of TM^\perp)

moreover $h|_Z: Z \rightarrow M$ is a diffeomorphism
 this implies h is a diffeomorphism on a suitably small
 nbhd N' of Z

Indeed: let $N_{1/n}$ be points in $T_M^\perp \leq \frac{1}{n}$ from Z

for some n $h|_{M_{1/n}}$ an embedding

if not then $\forall n \exists x_n, y_n \in M_{1/n}$ s.t. $x_n \neq y_n$
 and $h(x_n) = h(y_n)$

let $x = \lim x_n$ and $y = \lim y_n$ (exist by cptness)

$\therefore h(x) = h(y) \Rightarrow x = y$ (since $x, y \in Z$)

h a local diffeomorphism so \exists nbhd of $x = y$

where h is one-to-one, this contradicts $\exists x_n, y_n$



C. Approximations of continuous functions II

two continuous functions $f_0, f_1: X \rightarrow Y$ are called
homotopic if \exists a continuous map

$$F: X \times [0, 1] \rightarrow Y$$

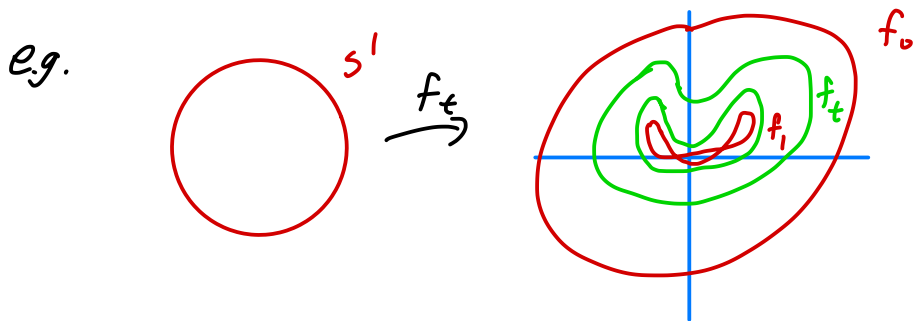
such that

$$F(x, 0) = f_0(x) \quad \forall x \in X$$

$$F(x, 1) = f_1(x)$$

we call F a homotopy

if we set $f_t: X \rightarrow Y: x \mapsto F(x, t)$ then we can think
 of F as giving a "continuous deformation"
 from f_0 to f_1 through the f_t 's



if X and Y are smooth manifolds and F is smooth then we call this a smooth homotopy

exercise: (smooth) homotopy is an equivalence relation

Th^m 5:

Suppose N and M are smooth manifolds
(M without boundary)

and $f: N \rightarrow M$ is continuous

Then f is homotopic to a smooth map.

If f is already smooth on a closed subset A
then the homotopy can be chosen to be
fixed on A .

Proof: we can assume $M \subset \mathbb{R}^k$ by the Whitney
embedding theorem

so $f: N \rightarrow M \subset \mathbb{R}^k$ is continuous

\exists a tubular nbhd $N(M)$ of M in \mathbb{R}^k

and $q: N(M) \rightarrow M$ its projection

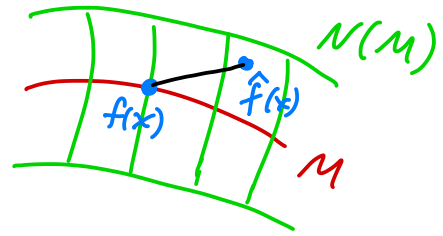
by Th^m 1 we know there is a smooth map $\hat{f}: N \rightarrow \mathbb{R}^k$
that is arbitrarily close to f

in particular $\text{im } \hat{f} \subset N(M)$

exercise: we can choose \hat{f} st.

$(1-t)f(x) + t\hat{f}(x)$ is in $N(M)$

$\forall t \in [0,1]$ and $x \in N$



so $F: N \times [0,1] \rightarrow M$

$(x,t) \mapsto (1-t)f(x) + t\hat{f}(x)$

is a homotopy from f to $g \circ \hat{f}$ and $g \circ \hat{f}$ is smooth!

moreover $\hat{f} = f$ on a closed set A where f is

smooth so homotopy fixed on A



Cor 6:

let $f_0, f_1: N \rightarrow M$ be two smooth maps

Then f_0 and f_1 are homotopic

\Leftrightarrow

they are smoothly homotopic

Proof: $(\Leftarrow) \checkmark$

(\Rightarrow) let $F: N \times [0,1] \rightarrow M$ be a homotopy

(smooth on $N \times \{0,1\}$)

Th $\text{Th}^m 5$ gives $\tilde{F}: N \times [0,1] \rightarrow M$ smooth

and $\tilde{F} = F$ on $N \times \{0,1\}$



D. Homotopy and Stability

frequently in math (and more so in physics...) we are interested in properties that are "stable" i.e. don't change under "small perturbations"

more precisely we say a property of a map

$$f_0: M \rightarrow N$$

is stable if for any smooth homotopy f_t of f_0 there is some $\epsilon > 0$ s.t. f_t also has this property for all $t < \epsilon$.

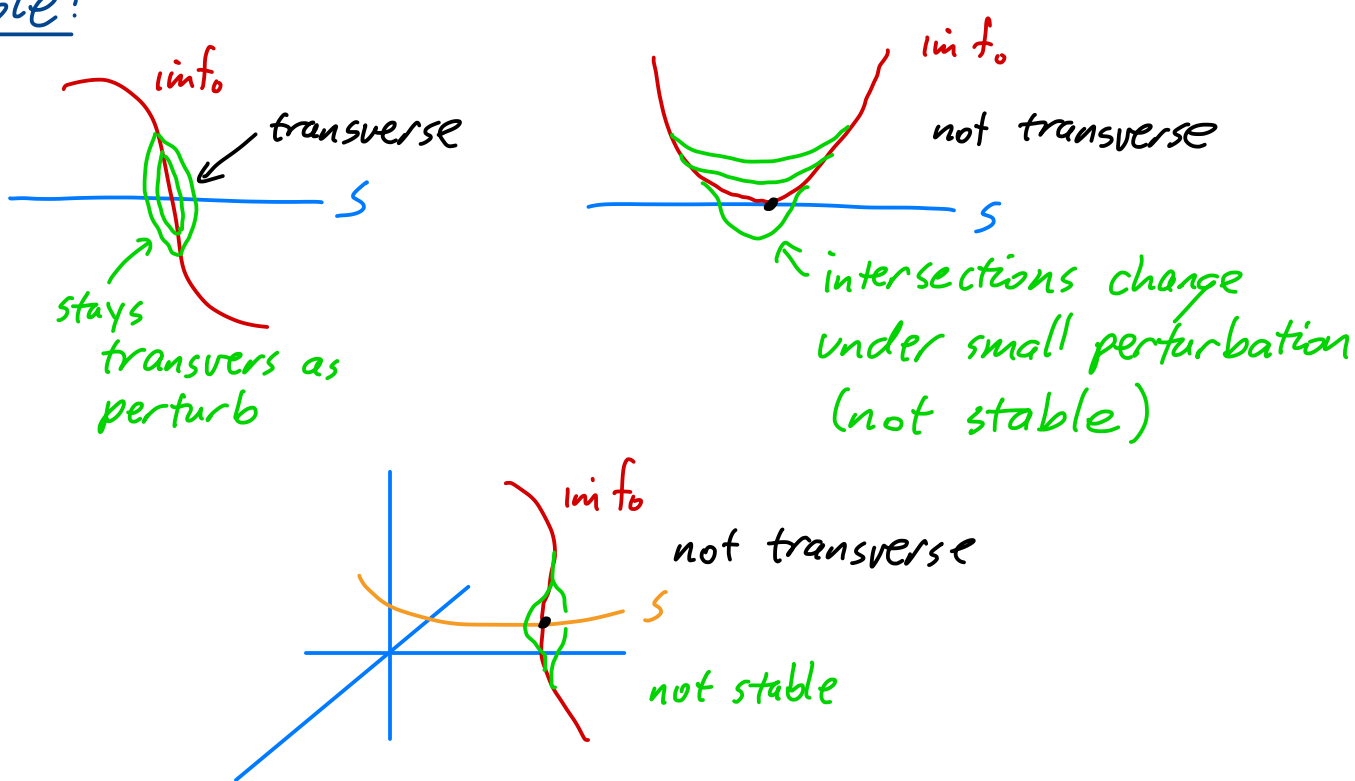
Th^m 7 (Stability Th^m):

The following properties of smooth maps from a compact manifold M to a manifold N are stable:

- (1) local diffeomorphism
- (2) immersions
- (3) submersions
- (4) maps transverse to a fixed closed submanifold $S \subset N$
- (5) embeddings
- (6) diffeomorphisms

recall (from homework) that $f: M \rightarrow N$ is transverse to $S \subset N$ if $\forall p \in f^{-1}(S)$ we have $T_{f(p)}N$ is spanned by $\text{im}(df_p)$ and $T_{f(p)}S$ and if f is transverse to S then $f^{-1}(S)$ is a manifold of $\text{codim} = \text{codim } S$ in N

example:



Proof: (2) let $F: M \times [0, 1] \rightarrow N$ be a smooth homotopy and $f_0(x) = F(x, 0)$ be an immersion we must find an $\epsilon > 0$ s.t. $\forall (x, t) \in M \times [0, \epsilon)$ $(df_t)_x$ is injective

recall lemma II.9 says if a linear map has max rank then near by linear maps do too

so for each $x \in M$, \exists a nbhd U_x of $(x, 0)$ in $M \times [0, 1]$
 st. $(df_t)_y$ is max rank $\forall (y, t) \in U_x$

now $U = \bigcup_{x \in M} U_x$ is an open nbhd of $M \times \{0\}$

so th^m follows!

items (1) and (3) have almost the same proof

as does (4) (once you do your homework)

now for (5) (6) is similar)

For a homotopy as above with f_0 an embedding

we know $\exists \varepsilon > 0$ st. f_t immersion for $t \in [0, \varepsilon)$

since M is compact we are done if we show

$\exists \varepsilon' > 0$ st. f_t is injective $\forall t \in [0, \varepsilon')$

to this end, assume not, so \exists a sequence

$$t_i \rightarrow 0 \text{ (decreasing)}$$

$$\text{and } x_i \neq y_i \in M \text{ st. } f_{t_i}(x_i) = f_{t_i}(y_i)$$

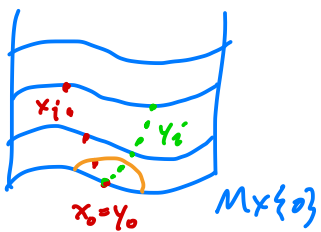
by compactness we have $x_i \rightarrow x$ (after passing to a subsequence)
 $y_i \rightarrow y$

$$\text{now } F(x_0, 0) = \lim_{i \rightarrow \infty} F(x_i, t_i) = \lim_{i \rightarrow \infty} F(y_i, t_i) = F(y_0, 0)$$

since f_0 injective $x_0 = y_0$

note: if $G: M \times I \rightarrow N \times I$
 $(x, t) \mapsto (F(x, t), t)$

$$\text{then } dG_{(x_0, 0)} = \left(\begin{array}{c|c} (df_0)_{x_0} & \begin{matrix} a_1 \\ \vdots \\ a_n \end{matrix} \\ \hline 0 \dots 0 & 1 \end{array} \right)$$



f_0 an immersion says df_0 has rank $= \dim M = m$

so $dG_{(x_0, 0)}$ has rank $m+1 = \dim (M \times [0, 1])$

so G is an immersion at $(x_0, 0)$

\therefore Th^m II.6 $\Rightarrow \exists$ nbhd about $(x_0, 0)$

st. G is one-to-one $\exists (x_i, t_i)$ and (y_i, t_i) 