

Symplectic Geometry

Given a manifold M

a symplectic structure on M is a 2-form $\omega \in \Omega^2(M)$

s.t. 1) ω is non-degenerate

(i.e. $\forall v \in T_x M, v \neq 0, \exists u \in T_x M, \text{ s.t. } \omega_x(v, u) \neq 0$)

2) $d\omega = 0$

the study of symplectic manifolds (M, ω) grew out of classical mechanics, but now is a thriving area of study with interesting connections to (low-dimensional) topology, Riemannian geometry and many other subjects

this class will cover the basics of symplectic geometry and then focus on understanding when a manifold admits a symplectic structure (area of current research)
if time permits we will also discuss contact manifolds (an odd dimensional version of symplectic manifolds).

I Symplectic Linear algebra

a symplectic vector space is a (finite dimensional) real vector space V with a non-degenerate, skew-symmetric bilinear form

$$\omega: V \times V \rightarrow \mathbb{R}$$

$$1) \omega(v, u) = -\omega(u, v)$$

$$2) \omega(v + cu, w) = \omega(v, w) + c\omega(u, w) \quad \forall c \in \mathbb{R}, v, u, w \in V$$

$$3) \omega(v, u) = 0 \quad \forall u \in V \Rightarrow v = 0$$

lemma 1:

a bilinear pairing $\omega: V \times V \rightarrow \mathbb{R}$ is non-degenerate

\Leftrightarrow

the linear map $\phi_\omega: V \rightarrow V^*: v \mapsto (f_v: V \rightarrow \mathbb{R}: u \mapsto \omega(v, u))$

is an isomorphism

Proof:

(\Rightarrow) $\phi_\omega(v) = 0$ then $f_\sigma: V \rightarrow \mathbb{M}: u \mapsto \omega(v, u)$

is the zero map and $v = 0$ by non-degeneracy

$\therefore \phi_\omega$ injective, \therefore isomorphism since $\dim V = \dim V^*$

(\Leftarrow) if $\omega(v, u) = 0 \forall u \in V$ then $\phi_\omega(v) = 0$ and $v = 0$ since

ϕ_ω an isomorphism 

example:

$$V = \mathbb{C}^n = \mathbb{R}^{2n}$$

$$h(v, u) = \sum \bar{v}_i u_i \quad \text{for } v = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix}, u = \begin{bmatrix} u_1 \\ \vdots \\ u_n \end{bmatrix}$$

\uparrow Hermitian form

note: $h(v, u) = \overline{h(u, v)}$

$$\begin{array}{ll} \text{set } \langle v, u \rangle = \operatorname{Re} h(v, u) & \text{symmetric} \\ \omega(v, u) = \operatorname{Im} h(v, u) & \text{skew-symmetric} \end{array} \left. \vphantom{\begin{array}{l} \langle v, u \rangle \\ \omega(v, u) \end{array}} \right\} \begin{array}{l} \text{both} \\ \text{non-degenerate} \end{array}$$

so \langle, \rangle is an inner product on V

ω is a symplectic structure on V

note: $\omega(v, u) = \langle v, u \rangle$

if $\{e_1, \dots, e_n\}$ is the standard basis for V over \mathbb{C}

and $f_j = i e_j$

then $\{e_1, f_1, \dots, e_n, f_n\}$ is a basis for V over \mathbb{R}
(positively oriented)

clearly $\omega(e_j, f_j) = -\omega(f_j, e_j) = \langle e_j, e_j \rangle = \langle f_j, f_j \rangle = 1$

all other other pairs evaluate to 0

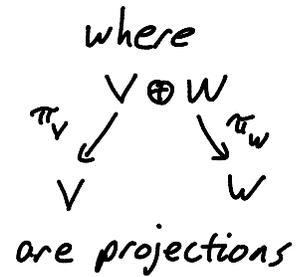
if $\{e_1^*, f_1^*, \dots, e_n^*, f_n^*\}$ is the dual basis for $(\mathbb{R}^{2n})^*$

$$\omega_{\text{std}} = \sum_{j=1}^n e_j^* \wedge f_j^*$$

\leftarrow standard symplectic structure on \mathbb{R}^{2n}

If $(V, \omega_V), (W, \omega_W)$ are symplectic vector spaces then $V \oplus W$ has symplectic structure

$$\omega = \pi_V^* \omega_V + \pi_W^* \omega_W$$



Th^m 2:

If (V, ω) a symplectic vector space then \exists an isomorphism $\phi: V \rightarrow \mathbb{C}^n$ s.t.

$$\phi^* \omega_{std} = \omega$$

we can immediately conclude

Cor 3:

- 1) any symplectic vector space is even dimensional
- 2) a skew-symmetric bilinear form $\omega: V \times V \rightarrow \mathbb{C}$ is non-degenerate $\Leftrightarrow \underbrace{\omega \wedge \dots \wedge \omega}_{n \text{ copies if } \dim V = 2n} \neq 0$
- 3) any symplectic vector space is canonically oriented (by $\omega \wedge \dots \wedge \omega$)
 - a) V, W symplectic \Rightarrow sympl. orientation on $V \oplus W$ is directsum orientation
 - b) symplectic orientation on \mathbb{C}^n is standard one

for the proof we need:

- (V, ω) symplectic vector space
- $W \subset V$ subspace

then $W^\perp = \{v \in V \mid \omega(v, u) = 0 \forall u \in W\}$

note: $\omega(v, v) = 0$ so $\dim W = 1 \Rightarrow W \subset W^\perp$

so quite different from inner product \perp but we still have

lemma 4:

$$\dim W + \dim W^\perp = \dim V$$

Proof: the map $\phi_\omega: V \rightarrow V^*$ is an isomorphism

so given $W \subset V$ the set $\phi_\omega(W^\perp) \subset V^*$ vanishes on W

so we have induced map

$$\tilde{\phi}_\omega: W^\perp \rightarrow (V/W)^*$$

we claim $\tilde{\phi}_\omega$ is an isomorphism

if so $\dim W^\perp = \dim (V/W)^* = \dim W$ and done!

injectivity: if $\tilde{\phi}_\omega(w) = 0$, then $\omega(w, v) = 0 \quad \forall v \in V$

$$\therefore w = 0$$

surjectivity: for any elt $\eta \in (V/W)^*$ gives a linear map

$$\eta: V \rightarrow \mathbb{R}$$

that vanishes on W

so $\exists v \in V$ st. $\phi_\omega(v) = \eta$ and $v \in W^\perp$

$$\therefore \tilde{\phi}_\omega(v) = \eta$$



Cor 5:

$$(W^\perp)^\perp = W$$

Proof: $W \subset (W^\perp)^\perp$ and same dimension



some terminology: $W \subset (V, \omega)$

if $W \subset W^\perp$ then W is isotropic ($\dim W \leq \frac{1}{2} \dim V$)

if $W \supset W^\perp$ then W is coisotropic ($\dim W \geq \frac{1}{2} \dim V$)

if $W = W^\perp$ then W is Lagrangian ($\dim W = \frac{1}{2} \dim V$)

if $\omega|_W$ is non-degenerate, then W is a symplectic subspace

exercise: $W \subset (V, \omega)$ is a symplectic subspace

\Leftrightarrow

$$W \cap W^\perp = \{0\}$$

\Leftrightarrow

$$W \oplus W^\perp = V \quad (\text{and } \omega = \pi_W^*(\omega|_W) + \pi_{W^\perp}^*(\omega|_{W^\perp}))$$

also note W symplectic $\Rightarrow W^\perp$ is symplectic

Proof of Th^m 2:

Induct on dimension V

dim $V = 0$: done

dim $V > 0$: then $\exists v \in V$ st. $v \neq 0$

ω non-degenerate $\Rightarrow \exists \tilde{u} \in V$ st. $\omega(v, \tilde{u}) \neq 0$

$$\text{let } u = \frac{\tilde{u}}{\omega(v, \tilde{u})}$$

note: $\omega(v, u) = 1$, $\omega(v, v) = 0$, $\omega(u, u) = 0$

so $W = \text{span}\{v, u\}$ is a symplectic subspace of V

v, u give isomorphism to $(\mathbb{C}, \omega_{\text{std}})$

$$\therefore V \cong (\mathbb{C}, \omega_{\text{std}}) \oplus (\mathbb{C}^{n-1}, \omega_{\text{std}}) \cong (\mathbb{C}^n, \omega_{\text{std}})$$

by induction

since $\dim W^\perp < \dim V$



if $(V, \omega_V), (W, \omega_W)$ are symplectic vector spaces then a linear map

$$f: V \rightarrow W$$

is symplectic if $f^* \omega_W = \omega_V$

note: f symplectic $\Rightarrow f$ is injective

$$(v \in \ker f \Rightarrow f(v) = 0 \perp W \Rightarrow v \perp V \Rightarrow v = 0)$$

Group of all symplectic linear maps of $(\mathbb{R}^{2n}, \omega_{\text{std}})$ is

$$Sp(2n, \mathbb{R})$$

note: $U(n) \subset Sp(2n, \mathbb{R})$ in fact maximal compact subgroup

$U(n) \hookrightarrow Sp(2n, \mathbb{R})$ a homotopy equivalence

Section II: Symplectic manifolds

recall a symplectic structure on a manifold M is a 2-form $\omega \in \Omega^2(M)$

- st. 1) ω is non-degenerate (on each $T_x M$)
 2) $d\omega = 0$

note: any symplectic manifold M is

- 1) even dimensional
- 2) oriented
- 3) has canonical volume form $\Omega = \omega \wedge \dots \wedge \omega$
- 4) $\exists a \in H^2(M; \mathbb{R})$ st. $a \cup \dots \cup a \neq 0$ cup product

M closed \uparrow since $d\omega = 0 \Rightarrow [\omega] \in H_{DR}^2(M) \cong H^2(M; \mathbb{R})$

and $\omega \wedge \dots \wedge \omega$ is a volume form
 so $\neq 0$ in $H_{DR}^{2n}(M)$

examples:

- 0) S^{2n} not symplectic if $n \neq 1$
 $S^2 \times S^{2m}$ not symplectic if $m \neq 0, 1$

1) $\mathbb{C}^n = \mathbb{R}^{2n} (x_1, y_1, \dots, x_n, y_n) \quad z_j = x_j + iy_j$

$\omega_{std} = \sum_{j=1}^n dx_j^{\wedge} dy_j^{\wedge}$ is a symplectic form, called the "standard" structure

$\omega = d\lambda$ where $\lambda = \frac{1}{2} \sum x_j dy_j - y_j dx_j = \frac{i}{2} \sum z_j d\bar{z}_j - \bar{z}_j dz_j$

- 2) Any oriented surface with an area form ω
 ($d\omega = 0$ for dim. reasons)

a submanifold N of a symplectic manifold (M, ω) is

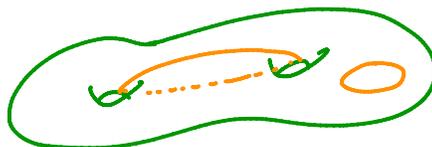
Lagrangian (isotropic, symplectic, coisotropic) if each $T_x N \subset T_x M$

is Lagrangian (isotropic, symplectic, coisotropic)

note: if $N \subset (M, \omega)$ is a symplectic submanifold then $(N, \omega|_{TN})$
 is a symplectic manifold.

examples:

- 1) any 1-dimensional manifold is isotropic
 so curves in a surface are Legendrian



- 2) any codimension 1 submanifold is coisotropic

3) $(M_1, \omega_1), (M_2, \omega_2)$ symplectic

then $M_1 \times M_2$ has symplectic structure $\pi_{M_1}^* \omega_1 + \pi_{M_2}^* \omega_2$
moreover $M_1 \times \{p\}$ and $\{q\} \times M_2$ are symplectic submanifolds

projections $M_1 \times M_2 \rightarrow M_i$

if $L_i \subset M_i$ a Lagrangian submanifold of (M_i, ω_i)
then $L_1 \times L_2$ a Lagrangian submanifold of $M_1 \times M_2$

eg. if Σ_1, Σ_2 surfaces w/ area forms then
 $\Sigma_1 \times \Sigma_2$ has lots of Lagrangian tori

$(M, \omega_M), (N, \omega_N)$ symplectic

a map $f: M \rightarrow N$ is called symplectic if $f^* \omega_N = \omega_M$

note: this implies df_x injective $\forall x \in M$
 $\therefore f$ an immersion

a symplectic diffeomorphism f is called a symplectomorphism
and is the natural equivalence relation on sympl. manifolds
(note, f^{-1} also symplectic)

example:

$(M_1, \omega_1), (M_2, \omega_2)$ symplectic

then $M_1 \times M_2$ has symplectic structure

$$\omega_{\lambda_1, \lambda_2} = \lambda_1 \pi_{M_1}^* \omega_1 + \lambda_2 \pi_{M_2}^* \omega_2$$

for any $\lambda_1, \lambda_2 \in \mathbb{R} - \{0\}$

given a map $f: M_1 \rightarrow M_2$, the graph of f is

$$\Gamma_f = \{ (x, f(x)) : x \in M_1 \} \subset M_1 \times M_2$$

exercise: a diffeomorphism $f: M_1 \rightarrow M_2$ is a symplecto.

\Leftrightarrow

Γ_f is Lagrangian in $(M_1 \times M_2, \omega_{1,-1})$

Important example:

let M be any smooth manifold

$\pi: T^*M \rightarrow M$ the projection map

the Liouville 1-form λ on T^*M

$$\lambda \in \Omega^1(T^*M)$$

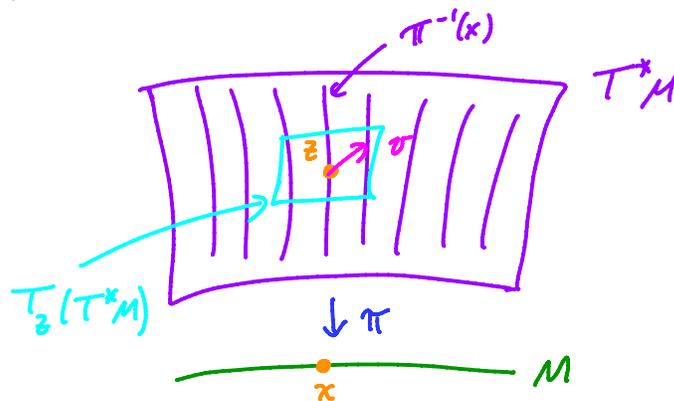
is defined as follows:

if $z \in T_x^*M$, then

$$z: T_{\pi(x)}M \rightarrow \mathbb{R}$$

if $v \in T_z(T^*M)$, then

$$d\pi_z(v) \in T_{\pi(x)}M$$



so $\lambda_z: T_z(T^*M) \rightarrow \mathbb{R}$
 $v \mapsto z(d\pi_z(v))$

exercise:

1) if q_1, \dots, q_n are local coordinates on $U \subset M$

then any $z \in T^*U \subset T^*M$ can be written

$$z = \sum_{i=1}^n p_i dq_i \quad \text{some } p_1, \dots, p_n \in \mathbb{R}$$

so $\{q_1, \dots, q_n, p_1, \dots, p_n\}$ are coordinates on T^*U

$$\text{and } \pi(q_1, \dots, q_n, p_1, \dots, p_n) = (q_1, \dots, q_n)$$

note: $dq_i = \pi^*dq_i$

q_i coordinate on T^*U so $dq_i \in \Omega^1(T^*U)$
 q_i coordinate on U so $dq_i \in \Omega^1(U)$

in our notation this makes sense but if confusing write $d\tilde{q}_i = \pi^*dq_i$

Show $\lambda = \sum_{i=1}^n p_i dq_i \quad (= \sum_{i=1}^n p_i d\tilde{q}_i)$

so $\omega = -d\lambda$ is a symplectic form on T^*M

2) If $\alpha \in \Omega^1(M)$ then $\alpha: M \rightarrow T^*M$

show $\alpha^* \lambda = \alpha$ (λ also called canonical 1-form)

3) image of zero section of T^*M Lagrangian

more generally, if $\alpha \in \Omega^1(M)$, then

image(α) Lagrangian $\Leftrightarrow d\alpha = 0$

4) fibers of $\pi: T^*M \rightarrow M$ are Lagrangian

5) If $f: M \rightarrow N$ a diffeomorphism, then

$f^*: T^*N \rightarrow T^*M$

is a symplectomorphism

Remark: This means you can try to distinguish smooth manifolds using symplectic geometry of their cotangent bundles!

interesting research problem: can you use this to distinguish exotic 4-manifolds?
other homeomorphic, but not-diffeomorphic pairs?

example: Abouzaid showed if M a $(4n+1)$ -manifold s.t. T^*M and T^*S^{4n+1} are symplectomorphic then M a homotopy sphere that bounds a manifold with trivial tangent bundle

This \Rightarrow symplectic geometry of cotangent bundles can distinguish 6 of 7 exotic smooth structures on S^9 from standard S^9

Major Open Question:

are M, N diffeomorphic
 \Leftrightarrow
 T^*M and T^*N are symplectomorphic

more Lagrangians in $(T^*M, d\lambda)$

if $S \subset M^n$ is a submanifold, then its conormal bundle

$$N^*S = \{ \eta \in T^*M : \pi(\eta) \in S, \eta(v) = 0 \ \forall v \in T_{\pi(\eta)}S \}$$

this is a bundle over S *covectors that vanish on S*

and a properly embedded submanifold of T^*M

exercise:

Hint: choose coordinates adapted to S at $x \in S$

- 1) $\dim N^*S = n - k$ (so fibers have $\dim n - k$)
- 2) N^*S is Lagrangian (even more $i^*\lambda = 0$ where $i: N^*S \rightarrow T^*M$)

example: if $x \in M$, then $N^*\{x\} = \pi^{-1}(x)$

note: if we have an isotopy S_t of S , then N^*S_t undergoes a proper isotopy through Legendrian submanifolds

so symplectic invariants of the Legendrian isotopy class of $N^*S \subset T^*M$ are invariants of the smooth isotopy class of $S \subset M$!

So we see T^*M contains lots of Lagrangian submanifolds, but conjecturally not lots of compact exact Lagrangian submanifolds

a Lagrangian submanifold $L \subset (T^*M, d\lambda)$ is exact if \exists a function $f: L \rightarrow \mathbb{R}$ such that $df = i^*\lambda$ (where $i: L \rightarrow T^*M$ inclusion)

Major Open Question:

let M be a compact manifold
if $L \subset (T^*M, d\lambda)$ a compact, orientable, exact Lagrangian
then L can be deformed through exact Lagrangians to the zero section?

if yes to this then yes to question on previous page.

this is Arnold's "nearby Lagrangian conjecture"

for our next example we need a few more ideas

recall an isotopy is a smooth map $\Phi: M \times (-a, a) \rightarrow M$ such that $\phi_t = \Phi(\cdot, t): M \rightarrow M$ is a diffeomorphism and $\phi_0 = \text{id}_M$ (a usually taken to be ∞)

given ϕ_t we get a time dependent vector field

$$v_t(p) = \left. \frac{d}{ds} \phi_s(q) \right|_{s=t} \text{ where } q = \phi_t^{-1}(p)$$

i.e. $v_t \circ \phi_t = \frac{d\phi_t}{dt}$ *

conversely given a time dependent vector field v_t (with compact support)
 then $\exists!$ isotopy $\Phi: M \times \mathbb{R} \rightarrow M$ satisfying $*$ called the flow of v_t

if v is time independent then flow satisfies

$$\phi_s \circ \phi_t = \phi_{s+t}$$

exercise:

the Lie derivative, defined by $\mathcal{L}_{v_t} \eta = \frac{d}{dt} (\phi_t^* \eta) \Big|_{t=0}$,
 where η is a k -form.

satisfies

$$\mathcal{L}_v \eta = L_v d\eta + dL_v \eta$$

Cartan magic formula

and

$$\frac{d}{dt} \phi_t^* \eta = \phi_t^* \mathcal{L}_{v_t} \eta$$

now given a symplectic form ω on M , the linear isomorphism $\phi_{\omega_x}: T_x M \rightarrow T_x^*(M)$
 gives an isomorphism

$$\Phi_\omega: \mathcal{X}(M) \rightarrow \Omega^1(M)$$

$$\uparrow v \longmapsto L_v \omega$$

vector fields on M

call a vector field v symplectic if $L_v \omega$ is closed

note: if v_t symplectic and ϕ_t its flow then

$$\frac{d}{dt} \phi_t^* \omega = \phi_t^* \mathcal{L}_{v_t} \omega = \phi_t^* (L_{v_t} d\omega + dL_{v_t} \omega) = 0$$

so ϕ_t preserves ω

i.e. $\phi_t: M \rightarrow M$ is a symplectomorphism

exercise:

if $\phi_t: M \rightarrow M$ flow of $v_t \in \mathcal{X}(M)$, then

ϕ_t a symplectomorphism $\forall t \iff v_t$ symplectic $\forall t$

a special type of symplectic vector field is a Hamiltonian vector field

given a function $H: M \rightarrow \mathbb{R}$

get $dH \in \Omega^1(M)$ a closed 1-form

let X_H be unique vector field such that

$$L_{X_H} \omega = dH \quad (\text{i.e. } \Phi^{-1}(dH))$$

X_H is called the Hamiltonian vector field of the energy (or Hamiltonian)
 function H

note: If $\gamma(t)$ a flow line of X_H , then $\gamma'(t) = X_H(\gamma(t))$

$$\begin{aligned} \text{so } \frac{d}{dt}[H(\gamma(t))] &= dH_{\gamma(t)}(\gamma'(t)) = \omega(X_H(\gamma(t)), \gamma'(t)) \\ &= \omega(X_H(\gamma(t)), X_H(\gamma(t))) = 0 \end{aligned}$$

so flow of X_H tangent to level sets of H

i.e. energy is conserved along flow

Physics aside:

in local coordinates $(q_1, \dots, q_n, p_1, \dots, p_n)$ on $T^*\mathbb{R}^n = \mathbb{R}^{2n}$

we have $\omega = -d\lambda = -\sum dp_i \wedge dq_i$

$$dH = \sum \left(\frac{\partial H}{\partial p_i} dp_i + \frac{\partial H}{\partial q_i} dq_i \right)$$

and

$$\iota_{X_H} \omega = -\sum (dp_i(X_H) dq_i - dq_i(X_H) dp_i)$$

$$\text{so } p_i\text{-coord of } X_H = -\frac{\partial H}{\partial q_i}$$

$$q_i\text{-coord of } X_H = \frac{\partial H}{\partial p_i}$$

or if $\gamma(t) = (q_1(t), \dots, q_n(t), p_1(t), \dots, p_n(t))$ is a flow line of X_H then

$$\begin{aligned} \dot{p}_i &= -\frac{\partial H}{\partial q_i} \\ \dot{q}_i &= \frac{\partial H}{\partial p_i} \end{aligned}$$

Hamilton's Equations

now if $V: M \rightarrow \mathbb{R}$ is some "potential energy" of some system

exerts a "force" $F = -\nabla V$

then the "total energy" is $H(q, p) = \frac{\|p\|^2}{2m} + V(p)$

in local coordinates get flow lines

$$\text{satisfy } \dot{q}_i = \frac{\partial H}{\partial p_i} = \frac{p_i}{m} \Rightarrow p_i = m \dot{q}_i \quad (\text{momentum} = \text{mass} \times \text{velocity})$$

$$\dot{p}_i = -\frac{\partial H}{\partial q_i} = -\frac{\partial V}{\partial q_i} \Rightarrow m \ddot{q}_i = \dot{p}_i = -\nabla V = F$$

Newton's equations!

now given a Hamiltonian $H: M \rightarrow \mathbb{R}$ for (M, ω)

from above X_H is tangent to level sets $H^{-1}(c)$

assume c a regular value so $H^{-1}(c)$ a manifold

Claim: X_H spans $(T(H^{-1}(c)))^{\perp \omega}$

indeed $v \in T_x(H^{-1}(c))$, then $\exists \gamma: (-\epsilon, \epsilon) \rightarrow H^{-1}(c)$ st. $\gamma(0) = x, \gamma'(0) = v$

and $0 = \frac{d}{dt}(H(\gamma(t))) = dH_{\gamma(t)}(\gamma'(t)) = \omega(X_H, v)$

so $X_H \in (TH^{-1}(c))^\perp$

but $\dim(TH^{-1}(c))^\perp = 1$

also note flow ϕ_t^H of X_H preserves ω

Important example:

recall complex projective space is

$\mathbb{C}P^n = \mathbb{C}^{n+1} - \{(0, \dots, 0)\} / \mathbb{C} - \{0\}$ where $\mathbb{C} - \{0\}$ acts on \mathbb{C}^{n+1} by multiplication

$\cong S^{2n+1} / S^1$
 ↑ unit sphere in \mathbb{C}^{n+1} ← unit sphere in \mathbb{C}

now if we set $H: \mathbb{C}^{n+1} \rightarrow \mathbb{R} : (z_0, \dots, z_n) \mapsto \sum_{i=0}^n |z_i|^2$ $z_j = x_j + iy_j$

then $S^{2n+1} = H^{-1}(1)$ ← regular value

note $dH = \sum 2(x_j dx_j + y_j dy_j)$

so $X_H = 2 \sum (-x_j \frac{\partial}{\partial y_j} + y_j \frac{\partial}{\partial x_j})$

now if $\gamma(t) = e^{it}(x_1 + iy_1, \dots)$ is an orbit of S^1 -action

then $\gamma'(0) = (-y_1 + ix_1, \dots)$

so vector field generating S^1 -action is $v = \sum -y_j \frac{\partial}{\partial x_j} + x_j \frac{\partial}{\partial y_j}$

since X_H proportional to v , orbits of X_H are orbits of S^1

so $\mathbb{C}P^n = S^{2n+1} / \text{orbits of } X_H$

exercise:

- 1) if (V, ω) symplectic vector space and $W \subset V$ coisotropic ($W^\perp \subset W$) then ω induces a symplectic structure on W/W^\perp
- 2) $x \in \mathbb{C}P^n$ and $z \in S^{2n+1}$ s.t. $\pi(z) = x$ ($\pi: S^{2n+1} \rightarrow \mathbb{C}P^n$ projection)

then $T_x \mathbb{C}P^n \cong T_z S^{2n+1} / T_z(S^1\text{-orbit}) = T_z(H^{-1}(1)) / (T_z(H^{-1}(1)))^\perp$

gets a symplectic structure from ω_z

since flow of X_H preserves ω show symplectic structure on $T_x \mathbb{C}P^n$ is independent of choice of z

also show this gives a smooth closed 2-form ω_{FS} on $\mathbb{C}P^n$

i.e. $\mathbb{C}P^n$ is a symplectic manifold

↑ Fubini-Study

this is an example of "symplectic reduction"

so $(\mathbb{C}P^n, \omega_{FS})$ symplectic manifold

$\mathbb{C}P^n$ is also a complex manifold and complex structure is "compatible" with ω_{FS} ↙ define later
so any complex submanifold of $\mathbb{C}P^n$ is a symplectic submanifold

example: given a collection of homogeneous complex polynomials in \mathbb{C}^{n+1}
 $p(\lambda z) = \lambda^d p(z)$

they have a well-defined zero locus in $\mathbb{C}P^n$

this is called a complex algebraic variety

if it is a manifold then it is a symplectic manifold

e.g. $\{\sum z_i^d = 0\}$ degree d hypersurfaces in $\mathbb{C}P^n$

Later we will consider many other constructions of symplectic manifolds
but for now move onto the "local theory".